AN13940

Connect i.MX RT1060 to USB 4G Module (RNDIS Mode)

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Document Information

Information	Content
Keywords	i.MX RT, RT, USB, 4G, LTE
Abstract	This application note discusses how to connect i.MX RT1060 EVK to Internet by USB 4G module like EC200A-CN from Quectel.

1 Introduction

There is one SDK example ***evkbmimxrt1060_lwip_dhcp_usb_bm*** in the i.MX RT1060 EVK SDK. It connects the USB to the Internet with the three cell phones mentioned in the guide. But if customer wants to use a USB 4G module, instead of a cell phone listed in the guide, to connect to the Internet, and it is possible that this example cannot work in such condition. Then we must adapt this example to new USB 4G module.

This application note discusses how to implement the adaption when the terminal becomes a USB 4G module like EC200A-CN from Quectel, and then connect to the Internet with this USB 4G module.

2 Basics

2.1 Introduction of RNDIS

Remote Network Driver Interface Specification (RNDIS) is a USB protocol defined by Microsoft. The windows OS can recognize the USB device which follows this specification automatically and treat it as a network device, as shown in Figure 1.

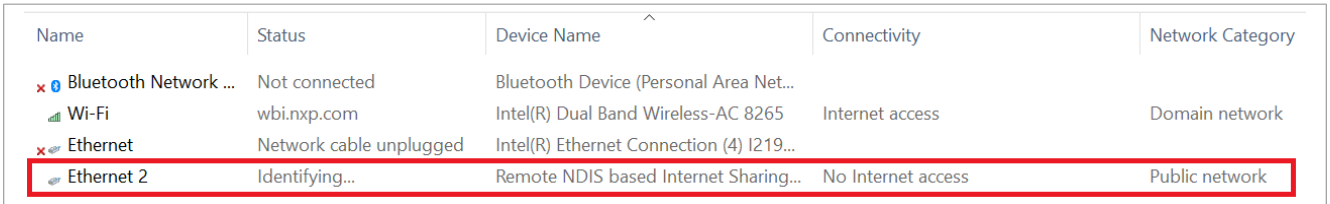

Figure 1. USB 4G module connected to windows

2.2 Network layer model for USB RNDIS

Figure 2 shows the network layer model for USB RNDIS.

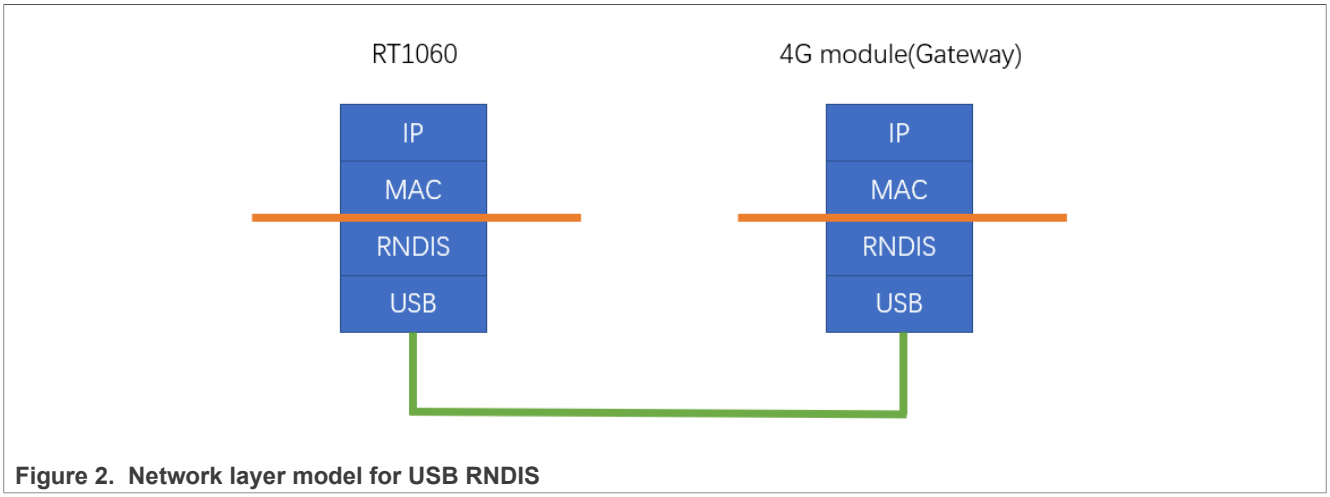

Figure 2. Network layer model for USB RNDIS

2.3 RNDIS interface/endpoint analysis

In the original SDK example, it uses two interfaces and three endpoints.

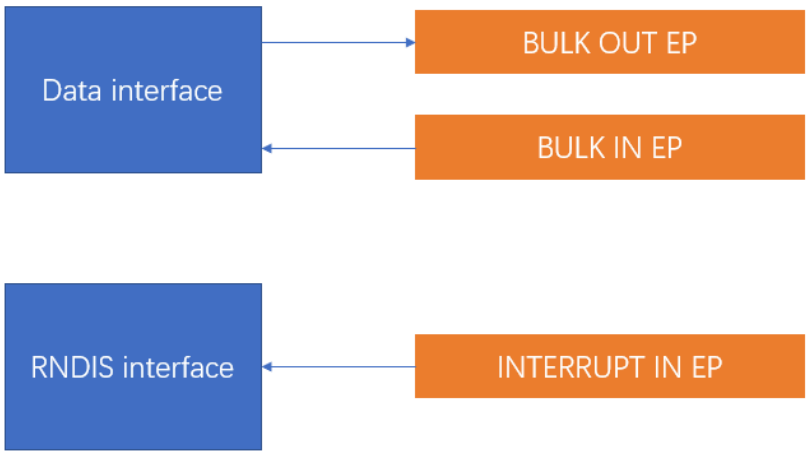

Figure 3. Endpoint used in default SDK example

Here, the data interface is used for Ethernet package communication, and there is one endpoint for each direction. RNDIS interface is used for device status polling.

2.4 EC200A-CN interface/endpoint analysis

EC200A-CN implements five interfaces, which include the interfaces introduced above.

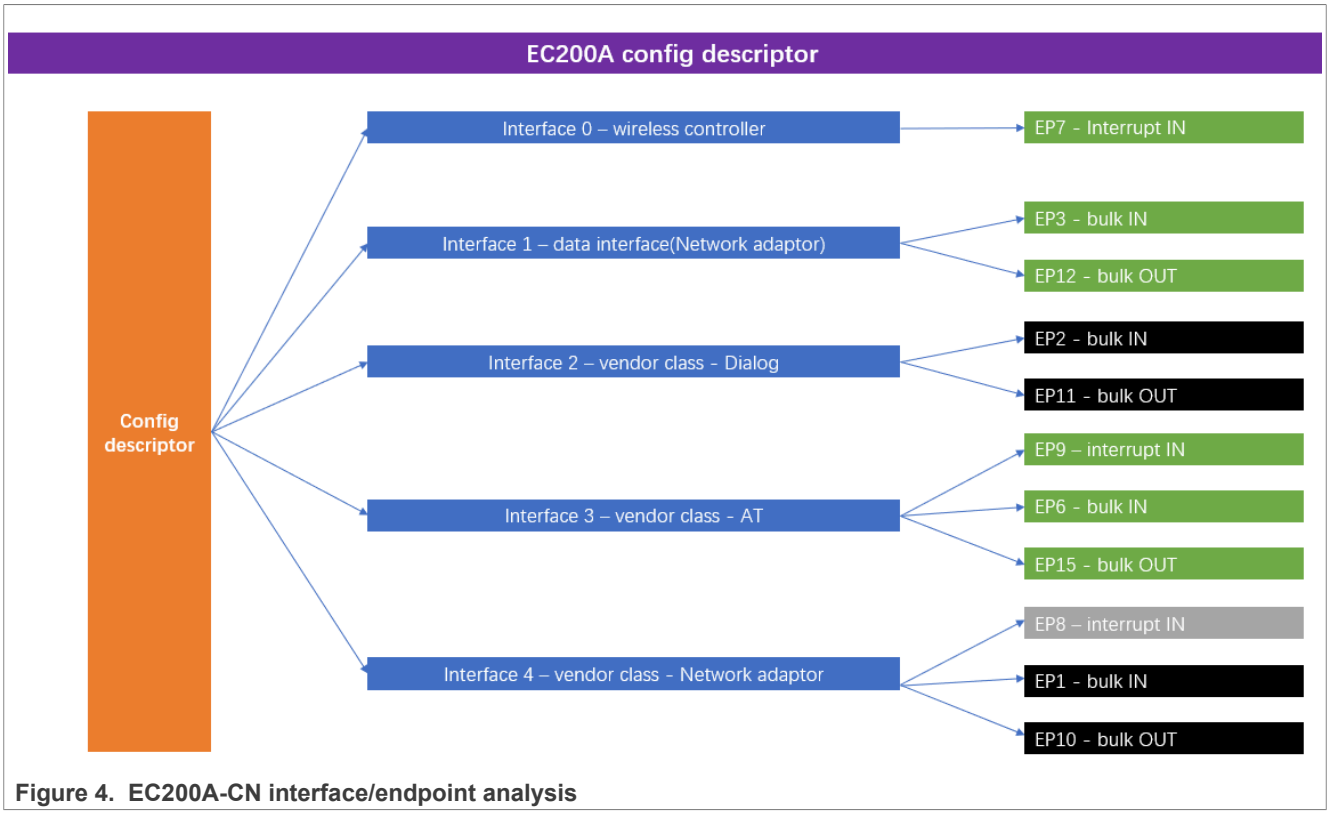

Figure 4. EC200A-CN interface/endpoint analysis

The additional interface used here is the AT interface.

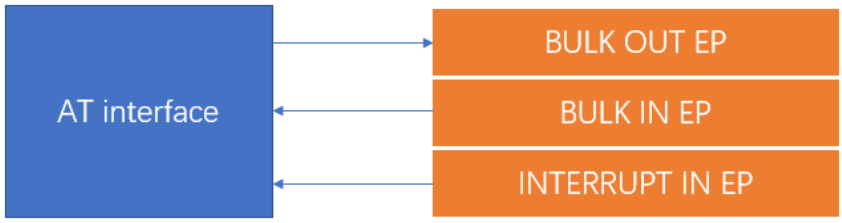

Figure 5. AT interface

The AT interface is used to dial (send AT command and get response), poll, and control the USB 4G module. We need poll the USB 4G module status and send the command to it to set it to the online mode. Then, the IP package from/to RT1060 EVK can be sent to/received from the Internet.

To enable/adapt to the new 4G module, we must:

- **Enable AT interface**
- **Dial on AT interface**

The other interfaces defined by the EC200A-CN are not important for us here, so they are not introduced in this document.

2.5 Some basics for USB host application by NXP SDK

- NXP SDK USB stack decodes the configuration descriptor automatically. It can detect all the interfaces and endpoints in the configuration descriptor.
  See `USB_HostParseDeviceConfigurationDescriptor()` in *usb/host/usb_host_devices.c*.
  Figure 6 shows the related call stack. Call stack analysis is useful for us to understand how the SDK USB stack is organized.

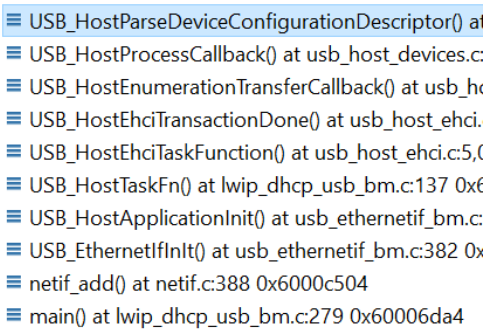

Figure 6. Call stack for `USB_HostParseDeviceConfigurationDescriptor()`

- For the event callback, see `USB_HostEvent()` in *lwip/port/usb_ethernetif_bm.c*.
  Figure 7 shows the related call stack.

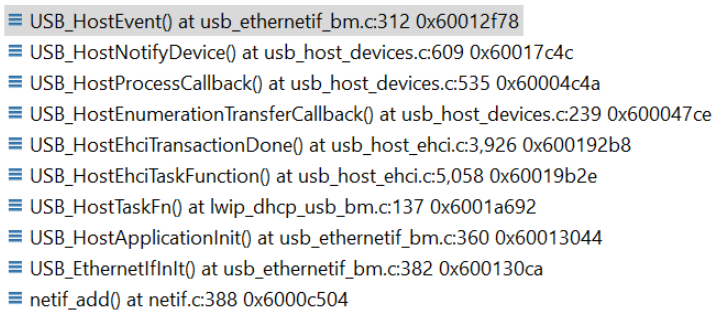

Figure 7. Call stack for `USB_ HostEvent ()`

- Open pipe for each interface.
  See `USB_HostCdcOpenDataInterfac()` and `USB_HostCdcOpenControlInterface()` in *usb_host_cdc.c*.
  Figure 8 shows the related call stack.

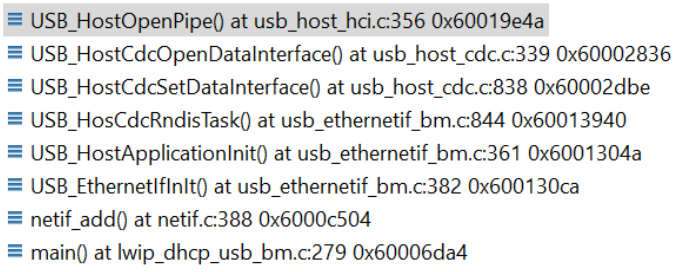

Figure 8. Call stack for `USB_ HostCdcOpenDataInterfac ()`

- State machine maintenance
  For state machine maintenance, refer to `USB_HosCdcRndisTask()` and `USB_HostCdcRndisControlCallback()` in *lwip/port/usb_ethernetif_bm.c*.
  Figure 9 shows the default state machine. Adjust it to enable the AT interface and dial on AT interface.

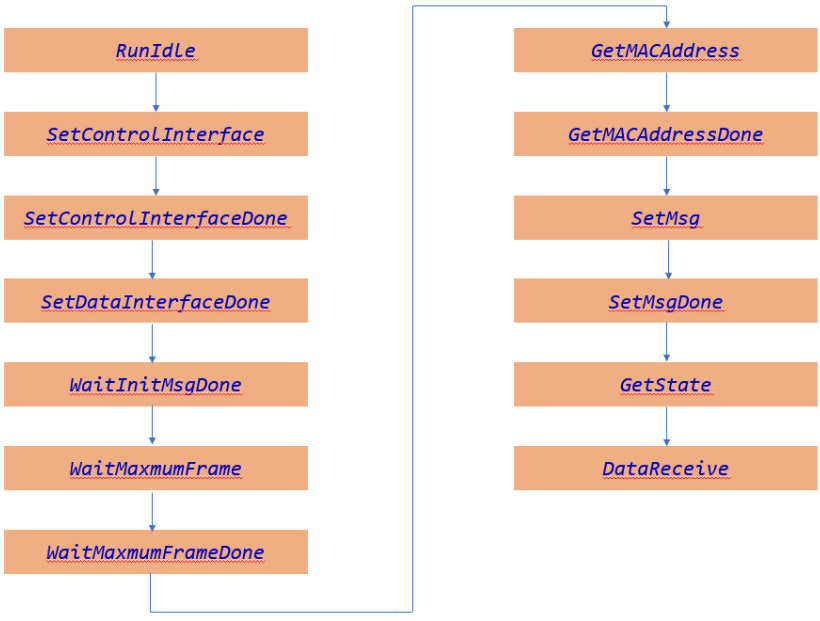

Figure 9. State machine maintenance

3 Details for implementation

Based on the introduction above, this section discusses the implementation details. Some code is presented here. For more details, see AN13940SW.

The main code changes are in:

- *usb_ethernet_bm.c*
- *usb_ethernet.h*

Some key code changes include:

- Add the data structure for AT interface.
  It is in *sdk_root\lwip\port\usb_ethernetif.h*.

```
typedef struct _usb_host_rndis_instance_struct
{
    usb_device_handle deviceHandle;
    usb_host_class_handle classHandle;
    usb_host_interface_handle controlInterfaceHandle;
    usb_host_interface_handle dataInterfaceHandle;
    usb_host_class_handle classHandle_at;
    usb_host_interface_handle dataInterfaceHandle_at;
```

Figure 10. Add the data structure for AT interface

- Add class initial code in attach event.
  It is in *lwip\port\usb_ethernetif_bm.c*.

```
case kStatus_DEV_Attached:
    rndisInstance->runState = kUSB_HostCdcRndisRunSetControlInterface;
    status = USB_HostCdcInit(rndisInstance->deviceHandle, &rndisInstance->classHandle);
    if(status == kStatus_USB_Success)
    {
        usb_echo("init cdc classHandle done. \r\n");
    }
    status = USB_HostCdcInit(rndisInstance->deviceHandle, &rndisInstance->classHandle_at
    if(status == kStatus_USB_Success)
    {
        usb_echo("init cdc classHandle_at done. \r\n");
    }
```

Figure 11. Add class initial code

- Add de-init code in de-attach event.
  It is in *lwip\port\usb_ethernetif_bm.c*.

```
case kStatus_DEV_Detached:
    rndisInstance->deviceState = kStatus_DEV_Idle;
    rndisInstance->runState = kUSB_HostCdcRndisRunIdle;
    USB_HostCdcDeinit(rndisInstance->deviceHandle, rndisInstance->classHandle);
    USB_HostCdcDeinit(rndisInstance->deviceHandle, rndisInstance->classHandle_at);
    rndisInstance->classHandle = NULL;
    rndisInstance->controlInterfaceHandle = NULL;
    rndisInstance->dataInterfaceHandle = NULL;
    rndisInstance->classHandle_at = NULL;
    rndisInstance->dataInterfaceHandle_at = NULL;
    rndisInstance->deviceHandle = NULL;
    rndisInstance->interruptRunState = kUSB_HostCdcRndisRunIdle;
    usb_echo("rndis device detached\r\n");
    break;
```

Figure 12. Add de-init code in de-attach event

- Update the state machine `enum` variable.
  It is in *lwip\port\usb_ethernetif.h*.

```
typedef enum HostCdcRndisRunState
{
    kUSB_HostCdcRndisRunIdle = 0,

    kUSB_HostCdcRndisRunSetControlInterface,
    kUSB_HostCdcRndisRunWaitSetControlInterface,
    kUSB_HostCdcRndisRunSetControlInterfaceDone,

    kUSB_HostCdcRndisRunSetDataInterface,
    kUSB_HostCdcRndisRunWaitSetDataInterface,
    kUSB_HostCdcRndisRunSetDataInterfaceDone,

    kUSB_HostCdcRndisRunSetATDataInterface,
    kUSB_HostCdcRndisRunWaitSetATDataInterface,
    kUSB_HostCdcRndisRunSetATDataInterfaceDone,

    kUSB_HostCdcRndisRunWaitInitMsg,
    kUSB_HostCdcRndisRunWaitInitMsgDone,
    kUSB_HostCdcRndisRunWaitGetMACAddress,
    kUSB_HostCdcRndisRunWaitGetMACAddressDone,
    kUSB_HostCdcRndisRunWaitMaxmumFrame,
    kUSB_HostCdcRndisRunWaitMaxmumFrameDone,
    kUSB_HostCdcRndisRunWaitSetMsg,
    kUSB_HostCdcRndisRunWaitSetMsgDone,

    // kUSB_HostCdcRndisRunEC200AInit,
    kUSB_HostCdcRndisRunWaitEC200AInit,
    kUSB_HostCdcRndisRunEC200AInitDone,

    // kUSB_HostCdcRndisRunDial,
    kUSB_HostCdcRndisRunWaitDial,
    kUSB_HostCdcRndisRunDialDone,
```

Figure 13. Update state machine

- Update state machine implementation function.
  It is in *lwip\port\usb_ethernetif_bm.c*.

```
case kUSB_HostCdcRndisRunSetDataInterfaceDone:
    rndisInstance->runWaitState = kUSB_HostCdcRndisRunWaitSetATDataInterface;
    rndisInstance->runState = kUSB_HostCdcRndisRunIdle;
    if (USB_HostCdcSetDataInterface(rndisInstance->classHandle_at,
                                    rndisInstance->dataInterfaceHandle_at,
                                    0,
                                    USB_HostCdcRndisControlCallback,
                                    rndisInstance) != kStatus_USB_Success)
    {
        usb_echo("set at interface error\r\n");
    }
    break;
```

Figure 14. Update state machine implementation function

- Add related API and callback. The function parameter is not displayed here. For more details, see AN13940SW.

```
USB_HostCdcRndisATInCallback();
USB_HostCdcRndisATOutCallback();
dial_tx();  // Send command on AT interface
dial_rx();  // Receive message from AT interface
lte_dial(); // Dial, then USB 4G module can connect to internet
USB_HostCdcRndisEC200ACallback();
ep0_communicate(); // API used for AT interface enablement, to send/receive
 command/message to/from EP0
init_ec200a(); // Initiate EC200A, then AT interface communication is available
```

- The maximum interfaces number is supported.
  The maximum interfaces number is different when connected to different USB 4G module. The update is required.
  For example, if using the LE910C1-EU, update the value to 8.

```
#define USB_HOST_CONFIG_CONFIGURATION_MAX_INTERFACE (8U)
```

Figure 15. Maximum interfaces number supported

  And for EC200A-CN used in this document, the default value, 5, can work directly.

- Implement the new state machine for AT interface enablement and dial on AT interface.
  The main code change is in function `USB_HostCdcRndisControlCallback()` and `USB_HosCdcRndisTask()` in *lwip\port\usb_ethernetif_bm.c*. For more details, see AN13940SW.

- Adapt AT interface.
  The AT data interface index is decoded from USB analyzer when connecting the USB 4G module to a PC. The code is from `USB_HostCdcRndisEvent()` in *lwip\port\usb_ethernetif_bm.c*, it assigns `interfaceList[3]` to the `g_RndisInstance`, `dataInterfaceHandle_at`, and implements the binding.

```
// at interface.
hostInterface = &configuration->interfaceList[3];
g_RndisInstance.dataInterfaceHandle_at = hostInterface;

g_RndisInstance.deviceHandle = deviceHandle;
if ((NULL != g_RndisInstance.dataInterfaceHandle)    &&
    (NULL != g_RndisInstance.controlInterfaceHandle) &&
    (NULL != g_RndisInstance.dataInterfaceHandle_at)
)
{
    status = kStatus_USB_Success;
}
else
{
    usb_echo("- 0001 \r\n");
    status = kStatus_USB_NotSupported;
}
break;
```

Figure 16. Bind AT interface

Run the code after all code changes, and we can see that the i.MX RT1060 EVK is connected to the Internet successfully with USB 4G module EC200A-CN.

```
+QIND: PB DONE


ec200a_rx_index = 3
PB DONE detected.
dial_state == 100.
AT+qnetdevctl=1,1,1
>>>TX: AT+qnetdevctl=1,1,1

dial_state == 101.
>>>RX: AT+qnetdevctl=1,1,1
ec200a_rx_index = 4
dial_state == 102.
>>>RX:
OK
tdevctl=1,1,1
ec200a_rx_index = 5
dial_state == 103.
>>>RX:
+QNETDEVSTATUS: 1

ec200a_rx_index = 6
end do not need to rx again.
dial done.

*************************************************
 DHCP example
*************************************************
 DHCP state       : SELECTING
 DHCP state       : REQUESTING
 DHCP state       : BOUND

 IPv4 Address     : 192.168.43.100
 IPv4 Subnet mask : 255.255.255.0
 IPv4 Gateway     : 192.168.43.1


  waiting for getting the IP Address....

 the IP Address of nxp.com is    : 223.119.214.147
ping: send
223.119.214.147


ping: recv
223.119.214.147
 60 ms
```

Figure 17. Connect to the Internet with USB 4G module EC200A-CN

4 Attention

Make sure that the power supply is enough for USB 4G module. In this case, the i.MX RT1060 EVK is powered with an external power adapter, instead of with a USB cable. Otherwise, the USB 4G module resets when it tries to enable the RF to connect to the Internet.

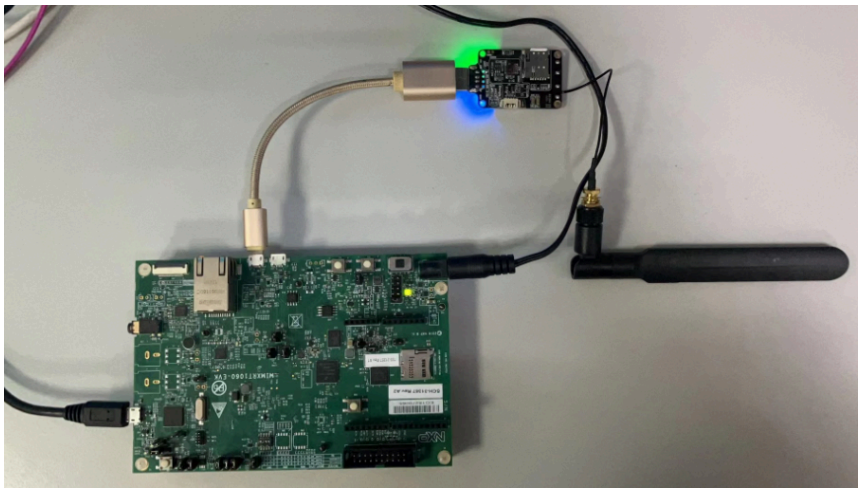

Figure 18. Power i.MX RT1060 EVK from external power adapter

5 Conclusion

This application note discusses the basic knowledge and details about how to connect i.MX RT1060 EVK to the Internet by USB 4G module EC200A-CN. It can be helpful for user reference when they want to connect to the Internet with the same or other USB 4G modules.

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